```
Vinclude <sldlib.h>
Vinclude <skring.h>
  int freq[ALAXPAROLA]; /* vettore di contato
delle frequenze delle lunghezze delle parol
```

Processes

Theoretical Aspects

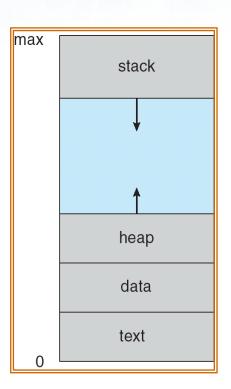
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Program

- Algorithm: a logical procedure that in a finite number of steps solves a problem
- Program: formal expression of an algorithm by means of a programming language
 - Sequence of code lines
 - Static entity

Process

- Process: a sequence of operations performed by a program in execution on a given set of input data.
 - Dynamic entity
 - Program in execution (running)
 - Text area (executable code)
 - Data area (global variables)
 - Stack (function parameters and local variables)
 - Heap (dynamic variables allocated during the process execution)
 - Registers (Program counter, stack pointer, etc.)

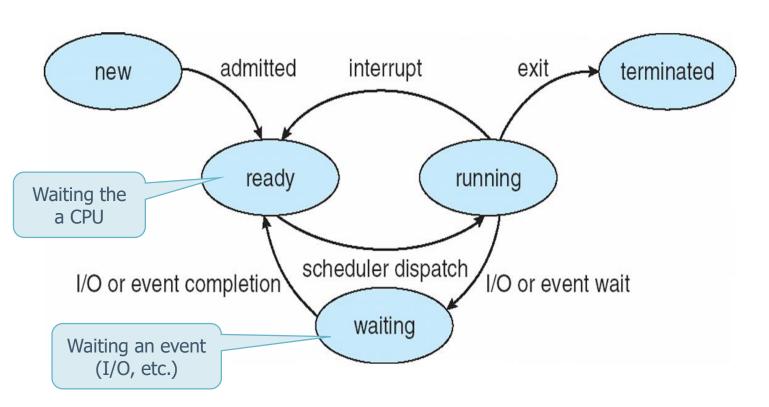


Process state

- During its execution a process change its state
 - > New: process is created and submitted to the OS
 - Running: a CPU is allocated to the process (in execution)
 - Ready: logically ready to run, waiting that a CPU is available
 - > Waiting: for an event or for resources
 - > **Terminated**: releases the resource it is using

State diagram

The possible state evolution of a process is described by a state diagram



Process Control Block (PCB)

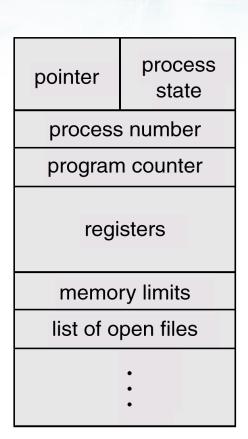
Process Control Block (PCB)

- The kernel stores for each process a set of data, e.g.,
 - > The process state
 - New, Ready, Running, Waiting, Terminated
 - Copy of the CPU registers
 - Their number and type is hardware-dependent
 - > The program counter
 - Address of the next instruction to be executed

pointer	process state
process number	
program counter	
registers	
memory limits	
list of open files	
	•

Process Control Block (PCB)

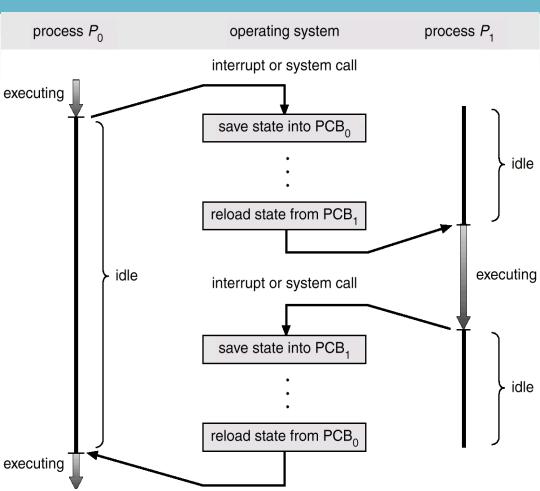
- Data useful for CPU scheduling
 - Priority, pointers to queues, etc.
- Data useful for memory management
 - Base register, Limit register, Segment and paging registers, etc.
- Signal table
 - signal handlers
- Various administration data
 - CPU usage, limits, etc.
- > I/O status information
 - I/O device list, open files, etc.



Context switching

- When the CPU is assigned to another process, the kernel
 - Save the state of the running process
 - Load the state previously saved for the new process
- The time devoted to this context switching is overhead, i.e., time not directly useful for any process
- The amount of time for context switching is hardware-dependent

Context switching



- Multiprogramming aims at maximizing the CPU usage by processes
- Processes can be classified as
 - > I/O-bound
 - Spend more time for I/0 than for computation
 - Require short CPU service times
 - CPU-bound
 - Spend more time for computation than for I/0
 - Require long CPU service times

- To maximize CPU usage, the kernel manages the sharing of the CPU among processes by means of a **scheduler**
 - ➤ A scheduler selects the next process to run, among the ready ones, according to a strategy that tries to maximize the CPU usage and to satisfy the response time for users
 - Examples
 - After a fork proceeds parent or child
 - When does a process end, which is the next one?
 - When does a process done I/O, which is the next one?

Different types of schedulers

- Long-term scheduler
 - Run less frequently
 - Rescheduling time in the order of seconds/minutes
 - Selects which process image can be inserted in the ready list, and loaded in main memory (swapper)
 - Controls the degree multiprogramming

➤ Short-term scheduler

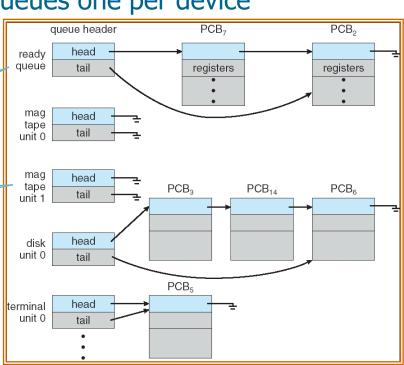
- Selects the next process to run (context-switching)
- Run frequently
- Rescheduling performed every 1 to 10 milliseconds
- Must be extremely fast

- A scheduler manages waiting processes by means of process queues
 - > There are several queues one per device
 - Each queue is a linked list

Ready process queue

I/O waiting process queue

To maximize the efficiency, each device has its own queue



Dynamic analysis of processes

Queuing diagram

The queuing diagram shows the possible process transitions from one queue to another one

