

```
#include <stdlib.h>
#include <string.h>
#include <ctype.h>
```

```
#define MAXPAROLA 30
#define MAXRIGA 80
```

```
int main(int argc, char *argv[])
```

```
{
    int freq[MAXPAROLA]; /* vettore di contatori
delle frequenze delle lunghezze delle parole */
    char riga[MAXRIGA];
    int i, inizio, lunghezza;
    FILE *f;
```

```
for(i=0; i<MAXPAROLA; i++)
    freq[i]=0;
```

```
if(argc != 2)
{
    printf(stderr, "ERRORE, serve un parametro con il nome del file\n");
    exit(1);
}
```

```
f = fopen(argv[1], "r");
if(f==NULL)
```

```
{
    printf(stderr, "ERRORE, impossibile aprire il file %s\n", argv[1]);
    exit(1);
}
```

```
while( fgets( riga, MAXRIGA, f ) != NULL )
```



# Synchronization

## Classical Synchronization Problems

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[skenz.it/os](http://skenz.it/os)

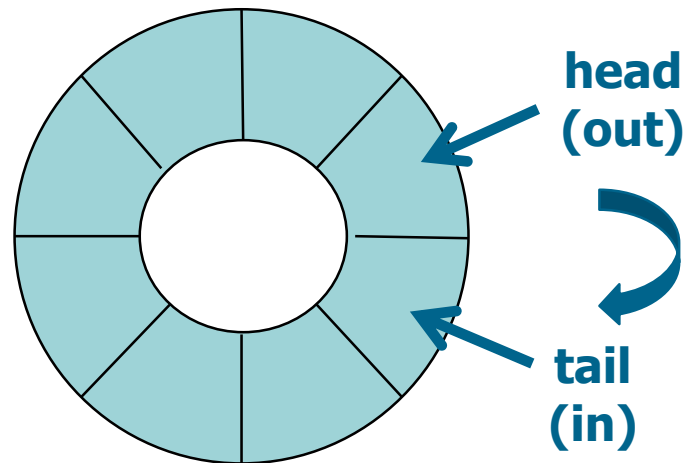
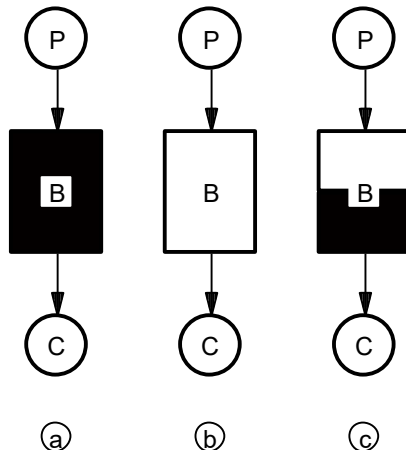
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# Producer-Consumer

## ❖ Producer and consumer with limited memory

- It uses a circular buffer of dimension **SIZE** to store the elements to be produced and consumed
- The circular buffer implements a FIFO queue (First-In First-Out)

full FIFO,  
empty,  
partially full



# Sequential access

```
#define SIZE ...  
...  
int queue[SIZE];  
int tail, head;  
...  
void init () {  
    tail = 0;  
    head = 0;  
    n = 0;  
}
```

FIFO standard (non ADT)

```
void enqueue (int val) {  
    if (n>SIZE) return;  
    queue[tail] = val;  
    tail=(tail+1)%SIZE;  
    n++;  
    return;  
}
```

```
void dequeue (int *val) {  
    if (n<=0) return;  
    *val=queue[head];  
    head=(head+1)%SIZE;  
    n--;  
    return;  
}
```

## Sequential vs parallel access

- ❖ In the sequential access **enqueue** and **dequeue** are concurrent
- ❖ In parallel access we can have two cases
  - **Only 1 producer and only 1 consumer**
    - The operations enqueue and dequeue act on different extremes of the queue, however the  $n$  variable is shared
  - **P producers and C consumers**
    - In addition to the previous case, concurrent access operations to the same extreme of the queue are possible

# Concurrent access: Version 1

- ❖ For parallel access with 1 producer and 1 consumer
  - You have to insert
    - A semaphore "full" that counts the number of filled elements
    - A semaphore "empty" that counts the number of empty elements
  - The counter n can be removed

# Concurrent access: Version 1

```
#define SIZE ...  
...  
int queue[SIZE];  
int tail, head;  
...  
void init () {  
    tail = 0;  
    head = 0;  
}
```

FIFO standard (non ADT)  
without the variable n

```
void enqueue (int val) {  
    queue[tail] = val;  
    tail=(tail+1)%SIZE;  
    return;  
}
```

```
void dequeue (int *val) {  
    *val=queue[head];  
    head=(head+1)%SIZE;  
    return;  
}
```

# Concurrent access: Version 1

1 Producer  
1 Consumer

Instead of n it uses  
# elements filled  
# elements empty

```
init (full, 0);  
init (empty, SIZE);
```

```
Producer () {  
    int val;  
    while (TRUE) {  
        produce (&val);  
        wait (empty);  
        enqueue (val);  
        signal (full);  
    }  
}
```

```
Consumer () {  
    int val;  
    while (TRUE) {  
        wait (full);  
        dequeue (&val);  
        signal (empty);  
        consume (val);  
    }  
}
```

## Concurrent access: Version 2

- ❖ Solution 1 is symmetric
  - The producer produces filled positions
  - The consumer produces empty positions
- ❖ It can be easily **extended** to the case where there are more producers and more consumers
  - Producers and consumers operates on opposite extremes of the buffer
    - It can be done **concurrently**
    - As long as the queue is not completely full or completely empty
  - Instead, two producers or two consumers must act in **mutual exclusion**



# Concurrent access: Version 2

P Producers  
C Consumers

It is necessary to force mutual exclusion between P and C

```
init (full, 0);  
init (empty, SIZE);  
init (MEp, 1);  
init (MEc, 1);
```

```
Producer () {  
    int val;  
    while (TRUE) {  
        produce (&val);  
        wait (empty);  
        wait (MEp);  
        enqueue (val);  
        signal (MEp);  
        signal (full);  
    }  
}
```

```
Consumer () {  
    int val;  
    while (TRUE) {  
        wait (full);  
        wait (MEc);  
        dequeue (&val);  
        signal (MEc);  
        signal (empty);  
        consume (val);  
    }  
}
```

# Readers & Writers

## ❖ Classical problem

- Courtois et al. [1971]
- Share data between two sets of concurrent processes
  - A set of **Readers**, which can access **concurrently** to the data
  - A set of **Writers**, which can access in **mutual exclusion**, both with other Writers and Readers processes, to the data
- Construct often used to create new synchronization primitives

# Readers & Writers

- ❖ There are two versions of the problem
  - Precedence to Readers
  - Precedence to Writers
- ❖ Common goals
  - Respect the precedence protocol
  - Maximize concurrency

## Precedence to Readers

- ❖ Giving precedence to Readers means
  - Privileging Readers access over Writers access, i.e.
  - Readers do not have to wait as long as a writer is in the CS
- ❖ Access protocol
  - Readers can concurrently access to the data
  - Until the Readers arrive, Writers have to wait
  - When even the last Reader ends, then you can wake up a writer (or a reader ... it depends on the scheduler)

# Precedence to Readers: Version 1

```
nR = 0;  
init (meR, 1);  
init (w, 1);
```

## Reader

```
wait (meR);  
  nR++;  
  if (nR==1)  
    wait (w);  
signal (meR);  
...  
reading  
...  
wait (meR);  
  nR--;  
  if (nR==0)  
    signal (w);  
signal (meR);
```

## Writer

```
wait (w);  
...  
writing  
...  
signal (w);
```

# Precedence to Readers: Version 2

## Reader

```
wait (meR);
  nR++;
  if (nR==1)
    wait (w);
signal (meR);
...
reading
...
wait (meR);
  nR--;
  if (nR==0)
    signal (w);
signal (meR);
```

```
nR = 0;
init (meR, 1);
init (meW, 1);
init (w, 1);
```

To enforce the precedence to R  
(the signal(w) unblocks an R)

## Writer

```
wait (meW);
wait (w);
...
writing
...
signal (w);
signal (meW);
```

## Conclusions

- ❖ The solution uses
  - A global variable ( $nR$ ) counts the number of Readers in the CS
  - A semaphore for the mutual exclusion for the access to the variable  $nR$  ( $meR$ )
  - A semaphore for the mutual exclusion of more Writers, or a Reader and the Writers ( $w$ )
  - Un semaforo di mutua esclusione per writer ( $meW$ )
- ❖ Writers are subject to **starvation**, because they can wait (be blocked) forever
- ❖ More complex solutions without starvation of the Writers are possible

## Precedence to Writers

- ❖ Giving priority to writers means
  - A Writer that is ready, must wait the smallest possible time
- ❖ Access protocol
  - Each Writer must wait that all Readers finish
  - Each Writer has a higher priority than every Reader



# Precedence to Writers

```
nR = nW = 0;
init (w, 1); init (r, 1);
init (meR, 1); init (meW, 1);
```

## Reader

```
wait (r);
wait (meR);
nR++;
if (nR == 1)
    wait (w);
signal (meR);
signal (r);
...
reading
...
wait (meR);
nR--;
if (nR == 0)
    signal (w);
signal (meR);
```

## Writer

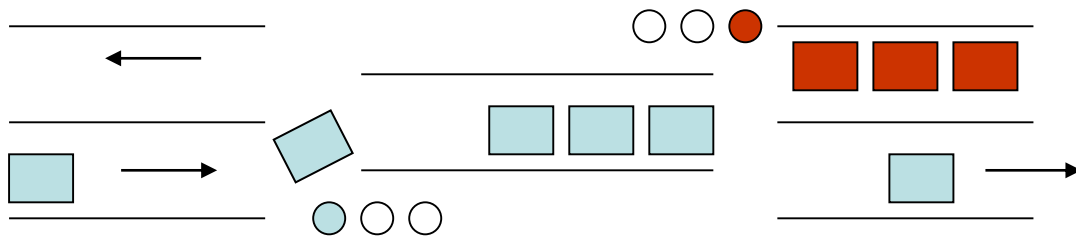
```
wait (meW);
nW++;
if (nW == 1)
    wait (r);
signal (meW);
wait (w);
...
writing
...
signal (w)
wait (meW);
nW--;
if (nW == 0)
    signal (r);
signal (meW);
```

## Conclusions

- ❖ The solution uses
  - Two global variables (nR and nW) to count the number of Readers and Writers
  - Two semaphores to guarantee mutual exclusion (meR and meW) for the access to the variables nR and nW
  - Two semaphores to guarantee mutual exclusion between Readers/Writers (r and w)
- ❖ Reader are subject to **starvation**, because they can wait (be blocked) forever
- ❖ More complex solutions without starvation are possible

# The "Alternate direction tunnel"

- ❖ In an alternate direction tunnel
  - Allow any number of cars (processes) to proceed in the same direction
  - If there is traffic in one direction, block traffic in the opposite direction



## The "Alternate direction tunnel"

- ❖ Extension to the Readers-Writers problem, with two sets of Readers
- ❖ Data structure
  - Two global counters ( $n1$  and  $n2$ ), one for each direction
  - Two semaphores ( $s1$  and  $s2$ ), one for each direction
  - A global semaphore for wait (busy)
- ❖ In its basic implementation, it can cause starvation of cars (in one direction with respect to the other)

## Solution

```
n1 = n2 = 0;
init (s1, 1); init (s2, 1);
init (busy, 1);
```

## left2right

```
wait (s1);
  n1++;
  if (n1 == 1)
    wait (busy);
signal (s1);
...
Run (left to right)
...
wait (s1);
  n1--;
  if (n1 == 0)
    signal (busy);
signal (s1);
```

## right2left

```
wait (s2);
  n2++;
  if (n2 == 1)
    wait (busy);
signal (s2);
...
Run (left to right)
...
wait (s2);
  n2--;
  if (n2 == 0)
    signal (busy);
signal (s2);
```

# Dining (5) philosophers problem

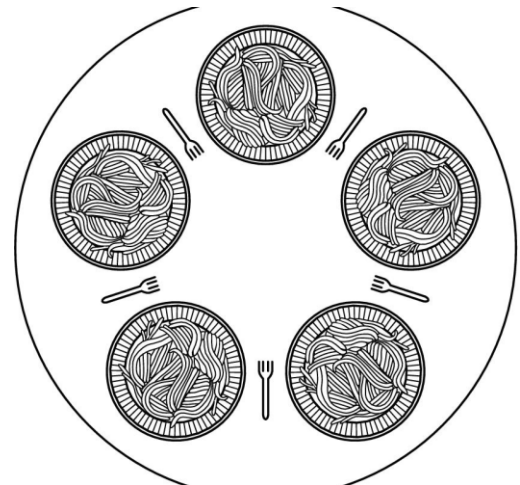
- ❖ Model in which different resources are common to different concurrent processes
- ❖ Due to Dijkstra [1965]
- ❖ Definition of the problem
  - A table is set with
    - 5 rice dishes
    - 5 (Chinese) chopsticks each between two plates
  - Around the table sit 5 philosophers
  - Philosophers **think** or **eat**
    - To eat each philosopher needs two chopsticks
    - Chopsticks can be obtained one at a time



## Model 0

## ❖ "Philosophical" solutions (not correct)

- Teach philosophers to eat with only 1 chopstick
- Provide more than 5 chopsticks
- Allow only at most to 4 philosophers to sit at the table
- Force asymmetry
  - Even position philosophers take the left fork first
  - Odd position philosophers take the right fork first

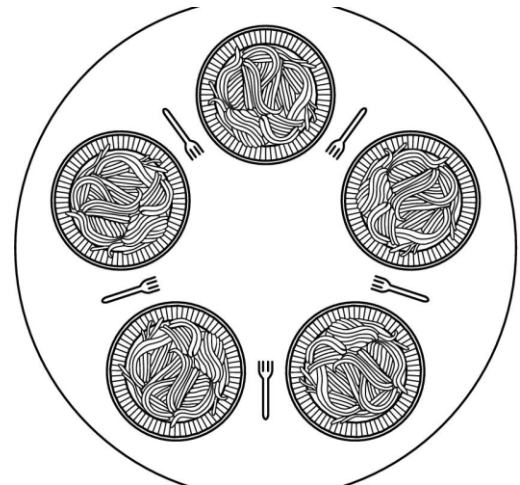


# Model 1

- ❖ Use one binary semaphore (mutex) to protect the access to the only resource "the food"
  - Cancel concurrency
  - Only one philosopher eats at the same time (in two could eat)

```
init (mutex, 1);
```

```
while (true) {  
    Think ();  
    wait (mutex);  
    Eat ();  
    signal (mutex);  
}
```





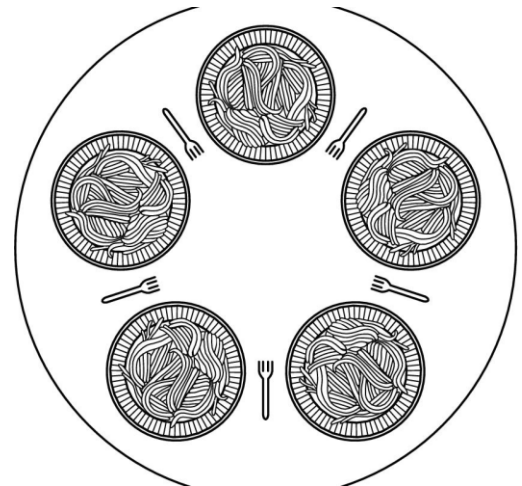
## Model 2

- ❖ A semaphore for each chopstick
  - It can cause deadlock

```
init (chopstick[0], 1);  
...  
init (chopstick[4], 1);
```

 $i \in [0, 4]$ 

```
while (true) {  
    Think ();  
    wait (chopstick[i]);  
    wait (chopstick[(i+1)mod5]);  
    Eat ();  
    signal (chopstick[i]);  
    signal (chopstick[(i+1)mod5]);  
}
```



## Solution

## ❖ Data structures

- A state for each philosopher (THINKING, HUNGRY, EATING)
- A semaphore for each philosopher (for access to food)
- Another semaphore to manage the access in mutual exclusion to the philosopher state variable

```
while (TRUE) {  
    Think ();  
    takeForks (i);  
    Eat ();  
    putForks (i);  
}
```

# Solution

```
int state[N]
init (mutex, 1);
init (sem[0], 0); ...; init (sem[4], 0);
```

```
takeForks (int i) {
    wait (mutex);
    state[i] = HUNGRY;
    test (i);
    signal (mutex);
    wait (sem[i]);
}
```

```
putForks (int i) {
    wait (mutex);
    state[i] = THINKING;
    test (LEFT);
    test (RIGHT);
    signal (mutex);
}
```

```
test (int i) {
    if (state[i]==HUNGRY && state[LEFT]!=EATING &&
        state[RIGHT]!=EATING) {
        state[i] = EATING;
        signal (sem[i]);
    }
}
```